Distributed Hypothesis Testing
Over Noisy Channels

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Abstract—A distributed binary hypothesis testing problem, in which multiple observers transmit their observations to a detector over noisy channels, is studied. Together with its own observations, the goal of the detector is to decide between two hypotheses for the joint distribution of the data. Single-letter upper and lower bounds on the optimal type 2 error exponent (T2-EE), when the type 1 error probability with the block-length are obtained. These bounds coincide and characterize the optimal T2-EE when only a single helper is involved. Our result shows that the optimal T2-EE depends on the marginal distributions of the data and the channels rather than their joint distribution. However, an operational separation between HT and channel coding does not hold, and the optimal T2-EE is achieved by generating channel inputs correlated with observed data.

I. INTRODUCTION

Statistical inference and learning have assumed prime importance in the fields of machine learning, data analytics and communications networks. An important problem arising in these scenarios is that of discerning the statistics of available data. This can be formulated as a hypothesis testing (HT) problem, in which the objective is to identify the underlying probability distribution of the data samples from among a set of candidate distributions. With the increasing adoption of distributed sensing technologies and the Internet of things (IoT) paradigm, the data is often collected from multiple remote locations and communicated to the detector over noisy communication links. This naturally leads to the problem of distributed statistical inference over noisy communication channels.

We study the problem of distributed binary HT over noisy channels depicted in Fig. 1. The detector is interested in determining whether the data \((U_1, \ldots, U_L, V, Z)\) is distributed according to the joint distribution \(P_{U_1 \ldots U_L V Z}\) or \(Q_{U_1 \ldots U_L V Z}\) corresponding to hypotheses \(H_0\) and \(H_1\), respectively. Each encoder \(l, l = 1, \ldots, L\), observes \(k\) samples independent and identically distributed (i.i.d) according to \(P_{U_l}\), and communicates its observation to the detector by \(n\) uses of the discrete memoryless channel (DMC), characterized by the conditional distribution \(P_{Y_l|X_l}\). The detector decides between the two hypotheses \(H_0\) and \(H_1\) based on the channel outputs \(Y_1^n, \ldots, Y_L^n\) as well as its own observations \(V^k\) and \(Z^k\). Our goal is to characterize the optimal type 2 error exponent (T2-EE) as a function of the bandwidth ratio, \(\tau = \frac{n}{k}\), under the constraint that the type 1 error probability is below a specified value. We will focus mostly on the special case in which \(P_{U_1 \ldots U_L V Z} = P_{U_1 \ldots U_L V | Z} P_Z\) and \(Q_{U_1 \ldots U_L V Z} = P_{U_1 \ldots U_L | Z} P_{V | Z} P_Z\), known as the testing against conditional independence (TACI) problem.

Distributed statistical inference under communication constraints was originally formulated by Berger in [1]. A simplified version is considered in [2], which studies binary HT for the model in Fig. 1 when \(L = 1\), \(Z\) is absent, and the channel between the encoder and the detector is a noise-free channel of rate \(R\). Ahlswede and Csiszár establish a single-letter characterization of the optimal T2-EE for the testing against independence (TAI) problem (including a strong converse), along with single-letter lower bounds for the general HT problem in [2]. For the same model, [3] provides a tighter lower bound on the T2-EE, which coincides with that of [2] for the TAI problem. An improved lower bound for the same problem is obtained in [4] by introducing “binning” at the encoder. HT for the model in Fig. 1 with noise free rate-limited channels is studied in [5], and the authors establish the optimality of binning for the TACI problem. A single-letter characterization of the optimal T2-EE for the multi-terminal TAI problem is obtained in [6] under a certain Markovian condition. In a slightly different setting with two decision centers, the optimal T2-EE for a three terminal dependence testing problem is characterized in [7]. The optimal T2-EE, when multiple interactions between the encoder and detector are allowed, is studied in [8],[9]. We remark here that all the above works consider rate-limited bit-pipes from the observers to the detector, and to the best of our knowledge, HT over noisy channels has not been studied previously.

**Notations:** The support of a random variable (r.v.) is denoted by calligraphic letters, e.g., \(\mathcal{X}\) for r.v. \(X\). The cardinality...
of $X^m$ is denoted by $|X^m|$. The joint distribution of r.v.'s $X$ and $Y$ is denoted by $P_{XY}$ and its marginals by $P_X$ and $P_Y$. $X - Y - Z$ denotes that $X$, $Y$, $Z$ form a Markov chain. For $m \in \mathbb{Z}^+$, $X^m$ denotes the sequence $X_1, \ldots, X_m$, while $X^n_i$ denotes $X_i, \ldots, X_n$ associated with observer $l$. The group of $m$ r.v.'s $X_{i, (j-1)m+1}, \ldots, X_{i, jm}$ is denoted by $X^m_{i,j}(j)$, and the infinite sequence $X^m_i(1), X^m_i(2), \ldots$ is denoted by $\{X^m_i(j)\}_{j \in \mathbb{Z}^+}$. Similarly, for a subset $S = \{l_1, \ldots, l_s\}$ of observers, $\{X^m_{l_1, i}, \ldots, X^m_{l_s, i}\}_j$ and $\{X^m_{l_1, j}, \ldots, X^m_{l_s, j}\}_{j \in \mathbb{Z}^+}$ are denoted by $X^m_{S, i}(S)$ and $X^m_{S, j}(S)$, respectively. Following the notation in [10], $T^n_{\bar{X}}$ (or $T^n_X$ when there is no ambiguity) denote the set of sequences of type $P$ and the set of $P_X$-typical sequences of length $m$, respectively. $D(P||Q)$ denotes the Kullback-Leibler (KL) divergence between distributions $P$ and $Q$ [10]. All logarithms are to the base 2. $I$ denotes the indicator function.

II. SYSTEM MODEL

All the r.v.'s considered henceforth are discrete with finite support. Let $k, n \in \mathbb{Z}^+$ be arbitrary. Let $L = \{1, \ldots, L\}$ denote the set of observers which communicate to the detector over orthogonal noisy channels, as shown in Fig. 1. For $l \in L$, encoder $l$ observes $U^L_{\tau, n}(l)$, and transmits $X^L_{\tau, n}(l)$, and transmits $X^L_{\tau, n}(l)$, where $\tau, n \in \mathbb{Z}^+$. The channel output $Y^L_{\tau, n}$ is given by the probability law $P_{Y^L_{\tau, n}}(y^L_{\tau, n}|x^L_{\tau, n}) = \prod_{l=1}^L \prod_{i=1}^\tau P_{Y_l}(y_l|x_i)$, i.e., the channels between the observers and the detector are orthogonal and discrete memoryless. Depending on the received symbols $Y^L_{\tau, n}$ and its own observations $(V^k, Z^k)$, the detector makes a decision between the two hypotheses $H_0 : P_{U_{\tau, n}V}Z$ or $H_1 : Q_{U_{\tau, n}V}Z$ according to the decision rule $g(n, k) : Y^L_{\tau, n} \times V^k \times Z^k \to \{0, 1\}$ given by $g(n, k)(y^L_{\tau, n}, v^k, z^k) = 1 (y^L_{\tau, n}, v^k, z^k) \in A^c$, where $A$ denotes the acceptance region for $H_0$. It is assumed that the r.v.'s $U_{\tau, n}, V$ and $Z$ have the same marginal distributions under both $H_0$ and $H_1$, that is $Q_{U_{\tau, n}V}Z(u_{\tau, n}, v, z) > 0$ for all $(u_{\tau, n}, v, z) \in U_{\tau, n} \times V \times Z$. In this paper, we focus mostly on the special case when $H_0 : P_{U_{\tau, n}V}ZP_{Z}$ and $H_1 : P_{U_{\tau, n}}|P_{Z}V_{\tau, n}P_{Z}$, i.e., TACI between $V$ and $U_{\tau, n}$ conditioned on $Z$.

Let $\tilde{\alpha}(k, n, f_1(k, n), \ldots, f_L(k, n), g(k, n)) \triangleq P_{Y^L_{\tau, n}V^kZ^k}(A^c)$ and $\alpha(k, n, f_1(k, n), \ldots, f_L(k, n), g(k, n)) \triangleq Q_{Y^L_{\tau, n}V^kZ^k}(A)$ denote the type 1 and type 2 error probabilities for the encoding function $f_1(k, n), \ldots, f_L(k, n)$ and decision rule $g(k, n)$, respectively. Define

$$\beta'(k, n, f_1(k, n), \ldots, f_L(k, n), \epsilon) \triangleq \inf_{g(k, n)} \beta(k, n, f_1(k, n), \ldots, f_L(k, n), g(k, n))$$

such that

$$\tilde{\alpha}(k, n, f_1(k, n), \ldots, f_L(k, n), g(k, n)) \leq \epsilon,$$ (2a)

and

$$(Z^k, V^k - U^k_{\tau, n} - X^n_{\tau, n}, l \in L),$$ (2b)

where $X^n_{\tau, n} = f_1(k, n)(U^k_{\tau, n})$ and

$$\beta(k, \tau, \epsilon) \triangleq \inf_{f_1(k, n), \ldots, f_L(k, n)} \beta\left(k, n, f_1(k, n), \ldots, f_L(k, n), \epsilon\right).$$ (3)

Note that $\beta(k, \tau, \epsilon)$ is a non-increasing function of $k$ and $\epsilon$.

A $T$-EE $k'$ is said to be $(\tau, \epsilon)$ achievable if there exists a sequence of integers $k$, encoding functions $f_1(k, n_k) : U^k \to \mathcal{X}^m_l$, $l \in L$, and decoding functions $g(k, n_k)$ such that $n_k \leq \tau k$, $\forall k$, and for any $\delta > 0$,

$$\limsup_{k \to \infty} \frac{\log \left(\beta(k, \tau, \epsilon)\right)}{k} \leq -(k' - \delta).$$ (4)

Let $\kappa(\tau, \epsilon) \triangleq \sup\{k' : k' \geq (\tau, \epsilon)\}$ is $(\tau, \epsilon)$ achievable.

For $k \in \mathbb{Z}^+$, we define

$$\theta(k, \tau) \triangleq \sup_{f_1(k, n), \ldots, f_L(k, n)} \frac{D(P_{Y^{L\tau}V^{k\tau}Z^k}\|Q_{Y^{L\tau}V^{k\tau}Z^k})}{k},$$

and

$$\theta(\tau) \triangleq \sup_{k} \theta(k, \tau).$$ (6)

In this paper, we obtain single-letter upper and lower bounds on $\kappa(\tau, \epsilon)$ for the TACI problem. It is shown that the two bounds coincide when $L = 1$. Our approach is similar to that in [2], where we first obtain bounds for $\kappa(\tau, \epsilon)$ in terms of $\theta$, and then show that $\kappa$ has a single-letter characterization in terms of information theoretic quantities. We establish this characterization by considering the joint source-channel coding (JSCC) problem with noisy helpers. The next lemma obtains the bounds for $\kappa(\tau, \epsilon)$ in terms of $\theta$.

**Lemma 1.** For any bandwidth ratio $\tau > 0$, we have

(i) $\limsup_{k \to \infty} \frac{\log(\beta(k, \tau, \epsilon))}{k} \leq -\theta(\tau), \forall \epsilon \in (0, 1)$.

(ii) $\lim_{\epsilon \to 0} \liminf_{k \to \infty} \frac{\log(\beta(k, \tau, \epsilon))}{k} \geq -\theta(\tau)$.

Proof: The proof is similar to that of Theorem 1 in [2]. We prove (i) here, and omit the proof of (ii) due to space limitations. Let $k \in \mathbb{Z}^+$ and $\epsilon > 0$ be arbitrary, and $\tilde{n}_k, j(k, \tilde{n}_k), l \in L$, and $\tilde{Y}_{\tilde{n}_k}$ be the channel block length, encoding functions and channel outputs respectively, such that $\theta(k, \tau) - D(P_{Y^{L\tau}V^{k\tau}Z^k}\|Q_{Y^{L\tau}V^{k\tau}Z^k}) < k\epsilon$. For each $l \in L$, the sequences $\left\{\tilde{Y}_{\tilde{n}_k}(j)\right\}_{j \in \mathbb{Z}^+}$ form an infinite sequence of i.i.d. r.v.'s indexed by $j$. Hence, by the application of Stein’s Lemma [2] to the sequences $\left\{\tilde{Y}_{\tilde{n}_k}(j), V^k(j), Z^k(j)\right\}_{j \in \mathbb{Z}^+}$, we have

$$\limsup_{j \to \infty} \frac{\log \left(\beta(k, \tau, \epsilon)\right)}{k_j} \leq -\left(\theta(k, \tau) - \epsilon\right).$$ (7)

For $m \geq k\epsilon$, $\beta(m, \tau, \epsilon) \leq \beta(k, \tau, \epsilon)$. Hence,

$$\limsup_{m \to \infty} \frac{\log(\beta(m, \tau, \epsilon))}{m} \leq \limsup_{j \to \infty} \frac{\log(\beta(k, \tau, \epsilon))}{k_j}.$$
\[ \theta(k, \tau) \leq -\left( \theta(k, \tau) - \epsilon \right). \]

Note that the left hand side (L.H.S) of the above equation does not depend on \( k \). Taking supremum with respect to \( k \) on both sides of the equation and noting that \( \epsilon \) is arbitrary, proves (i).

\[ \text{Part (ii) of Lemma 1 proves the achievability of the T2-EE } \theta(\tau) \text{ using Stein’s Lemma. In Appendix A, we show an explicit proof of the achievability by computing the type 1 and type 2 errors for a block-memoryless stochastic encoding function at the observer and a joint typicality detector.} \]

Part (i) of Lemma 1 implies that \( \theta(\tau) \) is an achievable T2-EE, it is in general not computable as it is characterized in terms of a multi-letter expression. However, as we will show below, for the TACI problem, single-letter bounds for \( \theta(\tau) \) can be obtained. By the memoryless property of the sequences \( V^k \) and \( Z^k \), we can write

\[ \theta(\tau) = H(V|Z) - \inf_{\{f_{i(k,n)},\ldots,f_{l(k,n)}\}_{k,n}} \frac{H(V^k|Y^k_n,Z^k)}{k} : \tag{8} \]

\[ (Z^k, V^k) - U^k_l - X^n_l - Y^n_l, \ \forall \ l \in \mathcal{L}, \]

where \( U^k_l = f_i(k,n)(U^k_l) \).

Although Lemma 1 implies that \( \theta(\tau) \) is an achievable T2-EE, it is in general not computable as it is characterized in terms of a multi-letter expression. However, as we will show below, for the TACI problem, single-letter bounds for \( \theta(\tau) \) can be obtained. By the memoryless property of the sequences \( V^k \)

\[ \theta(\tau) = H(V|Z) - \inf_{\{f_{i(k,n)},\ldots,f_{l(k,n)}\}_{k,n}} \frac{H(V^k|Y^k_n,Z^k)}{k} : \tag{8} \]

\[ (Z^k, V^k) - U^k_l - X^n_l - Y^n_l, \ \forall \ l \in \mathcal{L}. \]

In the next section, we introduce the \( L \)-helper JSCC problem and show that the multi-letter characterization of this problem coincides with obtaining the infimum in (8). The computable characterization of the lower and upper bounds for (8) then follows from the single-letter characterization of the \( L \)-helper JSCC problem.

### III. \( L \)-HELPERS JSCC PROBLEM

Consider the model shown in Fig. 2 where there are \( L + 2 \) correlated discrete memoryless sources \( (U_{\mathcal{L}}, V, Z) \) i.i.d. with joint distribution \( P_{U_{\mathcal{L}}, V, Z} \). For \( 1 \leq l \leq L \), encoder \( l \) observes the sequence \( U^k_l \) and transmits \( X^k_l = f_i(k,n)(U^k_l) \) over the corresponding noisy channel, where \( f_i(k,n) : U^k_l \rightarrow X^k_l \), whereas encoder \( L + 1 \) observes \( V^k \), and outputs \( f_{L+1}(V^k) \) \( f_{L+1} : V^k \rightarrow \mathcal{M} = \{1, \ldots, 2^{|R|}\} \). The decoder has access to side-information \( Z^k \), receives \( f_{L+1}(V^k) \) error-free, and also observes \( Y^k \), the output of the DMCs \( P_{Y_l|X_l} \), \( l \in \mathcal{L} \). The output of the decoder is given by the mapping \( g^{(k,n)} : Y^k \rightarrow \mathcal{M} \times 2^{|R|} \rightarrow \mathcal{V}^k \). The decoder is interested in reconstructing \( V^k \) losslessly. For a given bandwidth ratio \( \tau \), a rate \( R \) is said to be achievable for the \( L \)-helper JSCC problem if for every \( \lambda \in (0,1] \), there exist a sequence of numbers \( \delta_k \geq 0 \) with \( \lim_{k \to \infty} \delta_k = 0 \), encoders \( f_i^{(k,n)}(\cdot) \), \( i \in \mathcal{L} \), \( f_{L+1}^{(k,n)}(\cdot) \) and decoder \( g^{(k,n)}(\cdot,\cdot,\cdot) \), such that \( n_k \leq \tau k \) and

\[ \Pr \{ g^{(k,n)}(f_{L+1}^{(k,n)}(V^k), Y^k_n, Z^k) = V^k \} \geq 1 - \lambda, \]

\[ \text{and } \frac{\log((|M|)})}{k} \leq R + \delta. \]

The infimum of all achievable rates \( R \) for the \( L \)-helper JSCC problem with bandwidth ratio \( \tau \) is denoted by \( R(\tau) \).

Next, we show that the problem of obtaining the infimum in (8) coincides with the multi-letter characterization of \( R(\tau) \) for the \( L \)-helper JSCC problem. We define

\[ R_k \triangleq \inf_{\{f_{i(k,n)},\ldots,f_{l(k,n)}\}_{k,n}} \frac{H(V^k|Y^k_n,Z^k)}{k} : \tag{9} \]

\[ \text{s.t. } (Z^k, V^k) - U^k_l - X^n_l = f_i(k,n)(U^k_l) - Y^n_l, \ l \in \mathcal{L}. \]

**Theorem 3.** For the \( L \)-helper JSCC problem,

\[ R(\tau) = \inf_k R_k. \]

**Proof:** The proof is given in Appendix B. □

Having shown the equivalence between the multi-letter characterizations of \( \theta(\tau) \) for the TACI problem over noisy channels and \( R(\tau) \) for the \( L \)-helper JSCC problem, our next step is to obtain computable single-letter lower and upper bounds on \( \theta(\tau) \), which can then be used to obtain bounds on \( \theta(\tau) \). For this purpose, we use the source-channel separation theorem [11, Th. 2.4] for orthogonal multiple access channels. The theorem states that all achievable average distortion-cost tuples in a multi-terminal JSCC (MT-JSCC) problem over an orthogonal multiple access channel (MAC) can be obtained by the intersection of the rate-distortion region and the MAC region. We need a slight generalization of this result when there is side information \( Z \) at the decoder, which can be proved similarly to [11]. Note that the \( L \)-helper JSCC problem is a special case of the MT-JSCC problem with \( L + 1 \) correlated sources \( P_{U_{\mathcal{L}}, V} \) and side information \( Z \) available at the decoder, where the objective is to reconstruct \( V \) losslessly. Although the above theorem proves that separation holds, a single-letter expression is not available in general for the multi-
terminal rate distortion problem [12]. However, single-letter inner and outer bounds have been given in [12], which enable us to obtain single-letter upper and lower bounds on \( R(\tau) \) as follows.

**Theorem 4.** For \( l \in \mathcal{L} \), let \( C_l \triangleq \max_{p_{X_l}} I(X_l; Y_l) \) denote the capacity of the channel \( P_{Y_l|X_l} \), and \( \tau \) be the bandwidth ratio for the \( L \)-helper JSCC problem. Define

\[
R^l(\tau) \triangleq \inf_{W_L} \max_{S \subseteq \mathcal{L}} F_S,
\]

where

\[
F_S = H(V|W_{S^c}, Z) + I(U_S; W_S|W_{S^c}, V, Z) - \tau \sum_{l \in S} C_l
\]

for some auxiliary r.v.’s \( W_l \), \( l \in \mathcal{L} \), such that

\[
(Z, V, U_l, W_l) - U_t - W_t,
\]

\(|W_l| \leq |U_l| + 4, \) and for all subsets \( S \subseteq \mathcal{L} \),

\[
I(U_S; W_S|V, W_{S^c}, Z) \leq \tau \left( \sum_{l \in S} C_l \right) .
\]

Similarly, let \( R^o(\tau) \) denote the right hand side (R.H.S) of (10), when the auxiliary r.v.’s \( W_l \), \( l \in \mathcal{L} \), satisfy (12), \(|W_l| \leq |U_l| + 4 \) and

\[
(V, U_{l^c}, Z) - U_t - W_l .
\]

Then,

\[
R^o(\tau) \leq R(\tau) \leq R^l(\tau), \quad \text{as } (14)
\]

\[
H(V|Z) - R^l(\tau) \leq \theta(\tau) \leq H(V|Z) - R^o(\tau). \quad \text{(15)}
\]

**Proof:** From the source-channel separation theorem, an upper bound on \( R(\tau) \) can be obtained by the intersection of the Berger-Tung (BT) inner bound [12, Th. 12.1] with the capacity region \( (C_1, \ldots, C_L, C_{L+1}) \), where \( C_{L+1} \) is the rate available over the noiseless link from the encoder of source \( V \) to the decoder. Writing the BT inner bound explicitly, we obtain that for all \( S \subseteq \mathcal{L} \) (including the null-set),

\[
I(U_S; W_S|V, W_{S^c}, Z) \leq \sum_{l \in S} \tau C_l,
\]

\[
I(U_S; W_S|V, W_{S^c}, Z) + H(V|W_{S^c}, Z) \leq \sum_{l \in S} \tau C_l + C_{L+1},
\]

where the auxiliary r.v.’s \( W_L \) satisfy (11) and \(|W_l| \leq |U_l| + 4 \). Taking the infimum of \( C_{L+1} \) over all such \( W_L \) and denoting it by \( R^l(\tau) \), we obtain the second inequality in (14). The other direction in (14) is obtained similarly by using the BT outer bound [12, Th. 12.2]. Since \( R(\tau) \) is equal to the infimum in (8), substituting (14) in (8) proves (15).

The BT inner bound is tight for the two terminal case, when one of the distortion requirements is zero (lossless) [12, Ch.12]. Thus, we have the following result (for convenience, we drop the index 1 from the associated variables).

**Lemma 5.** For the TACI problem with \( L = 1 \) and bandwidth ratio \( \tau \),

\[
\theta(\tau) = \sup_{W} I(V; W|Z) \quad \text{(16)}
\]

such that \( I(U; W|Z) \leq \tau C \),

\[
(Z, V) - U - W, \ |W| \leq |U| + 4. \quad \text{(17)}
\]

**Proof:** Note that the Markov chain conditions in (11) and (13) are identical for \( L = 1 \). Hence,

\[
R^o(\tau) = R^o(\tau) = R(\tau). \quad \text{(19)}
\]

Using the BT inner bound in [12, Ch.12], we obtain \( R(\tau) \) as the infimum of \( R' \) such that

\[
H(V|Z, W) \leq R'
\]

\[
I(U; W|V, Z) \leq \tau C
\]

\[
H(V|Z, W) + I(U; W|Z) \leq \tau C + R',
\]

for some auxiliary r.v. \( W \) satisfying (18). Hence,

\[
R(\tau) = \inf_{W} \left( H(V|Z, W), \ H(V|W, Z) \right.
\]

\[
+ I(U; W|Z) - \tau C), \quad \text{(23)}
\]

such that (18) and (21) hold. We next prove that (23) can be simplified as

\[
R(\tau) = \inf_{W} H(V|Z, W) \quad \text{(24)}
\]

such that (17) and (18) are satisfied. This is done by showing that, for every r.v. \( W \) for which \( I(U; W|Z) > \tau C \), there exists a r.v. \( W' \) such that \( I(U; W'|Z) = \tau C \), \( H(V|W, Z) \leq H(V|W, Z) + I(U; W'|Z) - \tau C \) and (18) and (21) are satisfied with \( W \) replaced by \( W' \). Setting

\[
\tilde{W} = \begin{cases} W', & \text{with probability } 1-p, \\ \text{constant}, & \text{with probability } p, \end{cases}
\]

suffices, where we choose \( p \) such that \( I(U; \tilde{W}|Z) = \tau C \). The details will be presented in a longer version of this paper. Eqn. (16) now follows from (15), (19) and (24).

**Remark 6.** We note here that the single-letter T2-EE characterization in Lemma 5 exhibits a separation between the distributions of the data sources \( U, V, Z \) and the channel distribution \( P_{Y_1|X} \). Together with the fact that the optimal \( R(\tau) \) in the \( L \)-helper JSCC problem is achieved by separate source and channel coding, one might be inclined to assume that \( \theta(\tau) \) for the TACI problem over noisy channels can also be achieved by a communication scheme that performs independent HT and channel coding, and the optimal T2-EE can be obtained by simply replacing the rate constraints in the TACI T2-EE expressions in [5] with the corresponding channel capacity values. Although such a separate coding and decision scheme is attractive, the T2-EE analysis would involve a tradeoff between two competing error exponents, one being the T2-EE assuming that the channel code can be decoded without
an error, and the other being the reliability function \( E_r \) of the channel \( P_{Y|X} \) [10], and the corresponding T2-EE does not necessarily meet the optimal value obtained from Lemma 5.

IV. CONCLUSIONS

We have studied the T2-EE for the distributed HT problem over orthogonal noisy channels with side information available at the detector. For the special case of TACI, single-letter upper and lower bounds are obtained for the T2-EE, which are shown to be tight when there is a single observer in the system. It is interesting to note that the reliability function of the channel does not play a role in the T2-EE, and a strict operational separation between HT and channel coding does not apply in general, even though the optimal T2-EE can be evaluated using the marginal distributions of the data sources and the channels, rather than their joint distributions. Obtaining single-letter bounds for the general HT problem, and analyzing the error exponents in the Chernoff regime are some of the interesting problems for future research.

APPENDIX A

T2-EE USING JOINT TYPICALITY DETECTOR

Here, we provide the proof for the case \( L = 1 \). For given arbitrary positive integers \( k \) and \( n \) such that \( \ell = knR \), fix \( f_{k,j}^{(k,j,n)} = P_{X_{k,j}^n}[U_{k,j}] \). For any integer \( j \) and sequence \( u_{k,j} \), the observer transmits \( X_{k,j}^n = f_{k,j}^{(k,j,n)}(u_{k,j}) \) generated i.i.d. according to \( \prod_{j=1}^{n} P_{X_{k,j}^n}[U_{k,j}] = u_{k,j} \). The detector declares \( H_0 : P_{U_{k,j}V_{k,j}} \) if \( (Y_{k,j}^n, V_{k,j}, Z_{k,j}) \in T_{[Y_{k,j}^n, V_{k,j}, Z_{k,j}]}(\delta_j, 0 \rightarrow \infty) \) where \( (\hat{Y}_{k,j}, \hat{U}_{k,j}, \hat{V}_{k,j}, \hat{Z}_{k,j}) \sim P_{Y_{k,j}^n|U_{k,j}^{n-1}}P_{V_{k,j}^{n-1}}, Z_{k,j}^{n-1} \) and \( H_1 : Q_{U_{k,j}V_{k,j}} \) otherwise. To simplify the exposition, we denote \( (\hat{Y}_{k,j}, \hat{U}_{k,j}, \hat{V}_{k,j}, \hat{Z}_{k,j}) \) by \( W_{k,n} \) and \( T_{[Y_{k,j}^n, V_{k,j}, Z_{k,j}]} \), respectively. By the Markov lemma [12], type 1 error probability tends to zero as \( j \rightarrow \infty \). The type 2 error probability is bounded by

\[
\beta'(k, j, n, f_{k,j}^{(k,j,n)}, \epsilon) \leq \sum_{\hat{P} \in T_{[Y_{k,j}^n, V_{k,j}, Z_{k,j}]}(\delta_j, \epsilon)} \sum_{W_{k,n}} Q_{W_{k,n}^n}|\hat{P}|_{W_{k,n}^n}|\hat{P}|_{W_{k,n}^n} \leq (j + 1)W_{k,n}|2 - jB_{k,n}(j) \]

where \( B_{k,n}(j) \equiv \min_{\hat{P} \in T_{[Y_{k,j}^n, V_{k,j}, Z_{k,j}]}(\delta_j, \epsilon)} |\hat{P}|_{W_{k,n}^n} \), and (a), (b) and (c) follow from Lemmas 2.3, 2.6 and 2.2 in [10], respectively. Hence,

\[
\log \left( \beta'(k, j, n, f_{k,j}^{(k,j,n)}, \epsilon) \right) \leq - \frac{B_{k,n}(j)}{k} + \delta'_{k,n}(j),
\]

where \( \delta'_{k,n}(j) \equiv \frac{|W_{k,n}| \log(1+\epsilon)}{k} \) and \( |W_{k,n}| = |V|^n|V|^k|Z|^k \). Note that for any \( k \) and \( n \), \( \delta'_{k,n}(j) \rightarrow 0 \) as \( j \rightarrow \infty \). Also, since \( \delta_j \) is chosen such that it tends to 0 as \( j \rightarrow \infty \), \( B_{k,n}(j) \) converges to \( D(P_{W_{k,n}^n}||Q_{W_{k,n}^n}) \) by the continuity of \( D(\hat{P}||Q_{W_{k,n}^n}) \) in \( \hat{P} \) for fixed \( Q_{W_{k,n}^n} \). Since \( k, n \) and \( f_{k,j}^{(k,j,n)} \) are arbitrary, it follows from (4) and (6) that \( \theta(\tau) \) is an achievable T2-EE for any upper bound \( \epsilon \) on the type 1 error probability. It is easy to see that this scheme can be generalized to \( L > 1 \).

APPENDIX B

PROOF OF THEOREM 3

For the achievability part, consider the following scheme.

Encoding: Fix \( k, n \in \mathbb{Z}^+ \) and \( P_{X_{k,j}^n}[U_{k,j}] \) at encoder \( l \), \( l \in \mathcal{L} \). For \( j \in \mathbb{Z}^+ \), upon observing \( u_{k,j} \), encoder \( l \) transmits \( X_{k,j}^n = f_{k,j}^{(k,j,n)}(u_{k,j}) \) generated i.i.d. according to \( \prod_{j=1}^{n} P_{X_{k,j}^n}[U_{k,j}] = u_{k,j} \). Encoder \( L + 1 \) performs uniform random binning on \( V_k \), i.e., \( f_{k,j}^{(k,j,n)}(V_k) \rightarrow \mathcal{M} \). By uniform random binning, we mean that \( f_{k,j}^{(k,j,n)}(V_k) = m \), where \( m \) is selected uniformly at random from the set \( \mathcal{M} \).

Decoding: Let \( M \) denote the received bin index, and \( \delta > 0 \) be an arbitrary number. If there exists a unique sequence \( \hat{V}_k \) such that \( f_{k,j}^{(k,j,n)}(\hat{V}_k) = M \) and \( (\hat{V}_k, Y_{k,j}^n, Z_{k,j}) \in T_{[Y_{k,j}^n, V_k, Z_{k,j}]}(\delta_j, 0 \rightarrow \infty) \), then the decoder outputs \( g^{(k,j,n)}(M, Y_{k,j}^n, Z_{k,j}) = \hat{V}_k \). Else, an error is declared.

It can be shown that the probability of decoding error tends to 0 as \( j \rightarrow \infty \), if \( R > H(V_k^n|Z_k^n) + \delta \). Details will be presented in a longer version, along with the converse proof.

REFERENCES